Numerical Methods ITGS219

Lecture: Interpolation and Extrapolation Splines

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5.6 Splines

Another form of interpolation: this fits a curve in an interval where the data at the end of the interval **coincides** with the data points and also **matches** the available derivatives with the next interval.

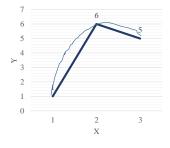
If we consider the points (x_i, f_i) and (x_{i+1}, f_{i+1}) and fit a straight line this will match the function values with the intervals on each side (but not necessarily the derivative).

We need to use a **higher-order curve**. In order to satisfy the requirements we need at least a **cubic**, and this is often the **preferred option**.

If we consider the **points** to be $(\mathbf{x}_i, \mathbf{f}_i)$ for i = 1 to N, we have N-1 intervals. Let us consider the cubic valid over the interval $[x_i, x_{i+1}]$ to be:

$$y_i(x) = a_i + (x - x_i)b_i + (x - x_i)^2 c_i + (x - x_i)^3 d_i.$$

We note that we have N-1 cubic equations each with four unknowns; that is <u>unknowns</u> = 4N-4 in total.



2

5.6 Splines ... cont.

The details of the conditions used to specify the values of the coefficients. Or to get the equations for unknowns = 4N-4 equations

1) we require that the cubic matches the data values at the ends of the interval:

$$y_i(x_i) = f_i$$
 and $y_i(x_{i+1}) = f_{i+1}$ for $i = 1, \dots, N-1$;

this in effect fixes the a_i and yields 2(N-1) equations.

2) we require the gradient and the curvature to match at the interior points:

$$y'_i(x_{i+1}) = y'_{i+1}(x_{i+1})$$
 and $y''_i(x_{i+1}) = y''_{i+1}(x_{i+1})$ for $i = 1, \dots, N-2$.

This yields a further 2(N-2) equations. Unfortunately we only have 4N-6 equations and as such our system is not totally specified.

3) We elect to consider **natural splines**, for which the curvature is taken to be zero at the ends of $y_{1}^{\prime\prime}$ the domain, that is

$$y_1''(x_1) = 0$$
 and $y_{N-1}''(x_N) = 0$.

So that we get the 4N-4 equations

5.6 Cubic Splines Example

Example Construct a natural cubic spline that passes through the points

$$y_i(x) = a_i + (x - x_i)b_i + (x - x_i)^2c_i + (x - x_i)^3d_i$$

[1,2];
$$S_0(x) = a_0 + b_0 (x-1) + c_0 (x-1)^2 + d_0 (x-1)^3$$

[2,3];
$$S_1(x) = a_1 + b_1(x-2) + c_1(x-2)^2 + d_1(x-2)^3$$
 8 unknowns
 $4(N-1) = 4(3-1) = 8$

1) cubic matches the data values at the ends

$$y_i(x_i) = f_i$$
 and $y_i(x_{i+1}) = f_{i+1}$ for $i = 1, ..., N-1$
gives $2(N-1) = 2(3-1) = 4$ equations

$$S_{0}(1) = 2 \implies a_{0} = 2$$
 7 unknowns to go

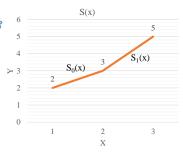
$$S_{0}(2) = 3 \implies a_{0} + b_{0} + c_{0} + d_{0} = 3 \implies b_{0} + c_{0} + d_{0} = 1$$
----(1)

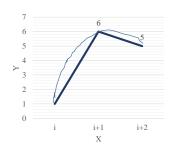
$$S_{1}(2) = 3 \implies a_{1} = 3$$
 6 unknowns to go

$$S_{1}(3) = 5 \implies 3 + b_{1} + c_{1} + d_{1} = 5 \implies b_{1} + c_{1} + d_{1} = 2$$
----(2)

| | i | <i>i+1</i> | <i>i+2</i> |
|---|---|------------|------------|
| Х | 1 | 2 | 3 |
| У | 2 | 3 | 5 |

cubic equations =
$$N-1 = 3-1 = 2$$





5.6 Cubic Splines Example

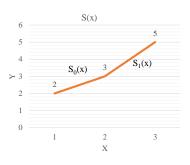
Example Construct a **natural cubic spline** that passes through the points $y_i(x) = a_i + (x - x_i)b_i + (x - x_i)^2c_i + (x - x_i)^3d_i.$

[1,2]; $S_0(x) = a_0 + b_0 (x-1) + c_0 (x-1)^2 + d_0 (x-1)^3$ [2,3]; $S_1(x) = a_1 + b_1 (x-2) + c_1 (x-2)^2 + d_1 (x-2)^3$

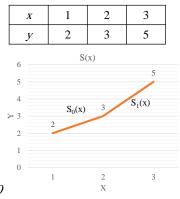
2) we require the gradient and the curvature to match at the interior points:

- $y'_i(x_{i+1}) = y'_{i+1}(x_{i+1})$ and $y''_i(x_{i+1}) = y''_{i+1}(x_{i+1})$ for *i=1,...,N-2* gives 2(N-2) = 2(3-2) = 2 equations
- $S_{0}'(x) = b_{0} + 2c_{0}(x-1) + 3d_{0}(x-1)^{2} \implies S_{0}''(x) = 2c_{0} + 6d_{0}(x-1)$ $S_{1}'(x) = b_{1} + 2c_{1}(x-2) + 3d_{1}(x-2)^{2} \implies S_{1}''(x) = 2c_{1} + 6d_{1}(x-2)$ $S_{0}'(2) = S_{1}'(2) \implies b_{0} + 2c_{0} + 3d_{0} = b_{1} \qquad \dots \dots (3)$ $S_{0}''(2) = S_{1}''(2) \implies 2c_{0} + 6d_{0} = 2c_{1} \qquad \dots \dots (4)$

| | i | <i>i+1</i> | <i>i+2</i> |
|---|---|------------|------------|
| X | 1 | 2 | 3 |
| У | 2 | 3 | 5 |



5.6 Cubic Splines Example



3) We elect to consider **natural splines**, for which the curvature is taken to be **zero** at the ends of the domain, that is

Boundary Condition $y_1''(x_1) = 0$ and $y_{N-1}''(x_N) = 0$. $S_{\theta}''(1) = \theta \implies c_{\theta} = \theta$ 5 unknowns to go And $S_1''(3) = \theta \implies 2c_1 + 6d_1 = 0$ ----(5) $b_0 + d_0 = 1$; $b_1 + c_1 + d_1 = 2$; $b_0 + 3d_0 = b_1$; $3d_0 = c_1$; $2c_1 + 6d_1 = 0$

 $b_0 + d_0 = 1$; $b_1 + c_1 + d_1 = 2$; $b_0 + 3d_0 - b_1 = 0$; $3d_0 - c_1 = 0$; $2c_1 + 6d_1 = 0$

2

3

3

5

1

2

Χ

у

5.6 Cubic Splines

Example Same Previous problem but instead of natural cubic spline lets fine the Clamped Cubic Spline if S'(1) = 2 and S'(3) = 1

$$S_0'(x) = b_0 + 2c_0 (x-1) + 3d_0 (x-1)^2$$

$$S_1'(x) = b_1 + 2c_1 (x-2) + 3d_1 (x-2)^2$$

Clamped Conditionals

$$S_{0}'(1) = 2 \implies b_{0} = 2$$
And
$$S_{1}'(3) = 1 \implies b_{1} + 2c_{1} + 3d_{1} = 1$$

$$S(x) = \begin{cases} 2 + \frac{3}{4}(x-1) + \frac{1}{4}(x-1)^{3} & ; x \in [1,2] \\ 3 + \frac{3}{2}(x-2) + \frac{3}{4}(x-2)^{2} - \frac{1}{4}(x-2)^{3} & ; x \in [2,3] \end{cases}$$

$$a_{0} = 2; \quad b_{0} + c_{0} + d_{0} = 1; \quad a_{1} = 3; \quad b_{1} + c_{1} + d_{1} = 2; \quad b_{0} + 2c_{0} + 3d_{0} = b_{1}; \quad 2c_{0} + 6d_{0} = 2c_{1}$$

$$a_{0} = 2; \quad c_{0} + d_{0} = -1; \quad a_{1} = 3; \quad b_{1} + c_{1} + d_{1} = 2; \quad b_{0} + 2c_{0} + 3d_{0} = b_{1}; \quad 2c_{0} + 6d_{0} = 2c_{1}$$

$$s(x) = \begin{cases} 2 + 2(x-1) - \frac{5}{2}(x-1)^{2} + \frac{3}{2}(x-1)^{3} & ; x \in [1,2] \\ 3 + \frac{3}{2}(x-2) + 2(x-2)^{2} - \frac{3}{2}(x-2)^{3} & ; x \in [2,3] \end{cases}$$

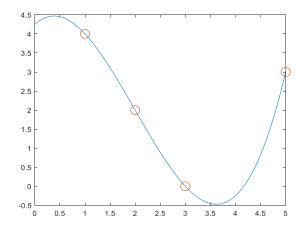
5.6 Splines with MATLAB

We can construct a matrix system in order to determine the coefficients. This can be coded: however the algorithm is quite involved and again Matlab comes to our rescue with the command *spline*.

Example 5.4 Fit a **cubic spline** to the data x = (1, 2, 3, 5), f = (4, 2, 0, 3) and plot the interpolated function on a grid $z = 0, 0.1, 0.2, \cdots, 5$.

x = [1 2 3 5];f = [4 2 0 3]; z = 0:0.1:5; y = *spline*(x,f,z); plot(z,y,x,f,'o','MarkerSize',12)

This yields the next figure



5.6 Splines with MATLAB

By way of illustration we shall now *construct* the *splines* through the *points* (x_1, y_1) , (x_2, y_2) , (x_3, y_3) . These **curves** are taken to have the equations.

$$y_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3$$
; where j = 1, 2 and 3

This gives us 12 undetermined coefficients and we shall now describe the equations which they satisfy.

| $y_i(x_i) = f_i$, j = 1, 2, 3: | | | | | | | | |
|---|--|--------|--|--|--|--|--|--|
| This represents the condition that the spline goes through the data | | | | | | | | |
| point at its left-hand end and these give the equations: | $a_1 = f_1,$ | (5.3a) | | | | | | |
| | $a_2 = f_2,$ | (5.3b) | | | | | | |
| | $a_3 = f_3.$ | (5.3c) | | | | | | |
| $y_j(x_{j+1}) = f_{j+1}$, j = 1, 2, 3: | $a_3 = f_3.$ | | | | | | | |
| This gives a similar condition at the right-hand ends: | $a_1 + h_1 b_1 + h_1^2 c_1 + h_1^3 d_1 = f_2,$ | (5.3d) | | | | | | |
| | | | | | | | | |
| | $a_2 + h_2 b_2 + h_2^2 c_2 + h_2^3 d_2 = f_3,$ | (5.3e) | | | | | | |
| Here we have introduced $h_j = x_{j+1} - x_j$ for convenience | $a_3 + h_3 b_3 + h_3^2 c_3 + h_3^3 d_3 = f_4.$ | (5.3f) | | | | | | |
| $y'_j(x_{j+1}) = y'_{j+1}(x_{j+1})$; j = 1, 2: | | | | | | | | |

This is the matching of the first derivative at the internal points,

5.6 Splines with MATLAB

This is the matching of the first derivative at the internal points, which gives

 $b_1 + 2h_1c_1 + 3h_1^2d_1 = b_2,$ (5.3g)

$$b_2 + 2h_2c_2 + 3h_2^2d_2 = b_3. \tag{5.3h}$$

 $y_{j}''(x_{j+1}) = y_{j+1}''(x_{j+1}), \quad j = 1, 2:$ This is a similar condition for the second derivative at the internal points: $2c_1 + 6h_1d_1 = c_2, \qquad (5.3i)$ $2c_2 + 6h_2d_2 = c_3. \qquad (5.3j)$ These are the conditions that the *splines* at the *ends* of the domain are *linear* at the end points, which gives: $2c_3 + 3h_3d_3 = 0. \qquad (5.3l)$

The solution of the above equations gives the required coefficients. Notice that these coefficients could also have been retrieved using the *spline* command and then using the elements of the answer *coefs*

Note that the coefficients correspond to a cubic without the $-x_i$ factors. pp = spline(x,f);This is an example of an object rather than a variable, that is pp. pp.coefs ai b_i c_i di ans =0.2917 -0.8750 -1.4167 4.0000 -2.2917 0.2917 0 2.0000 0.2917 0.8750 -1.4167 0

